

DR-216
TECHNICAL MANUAL

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SECTION 1 - GENERAL

Dataram Corporation's Model DR-216 Semiconductor Memory System operates in Digital Equipment Corporation's Q-BUS based minicomputers, including the MICRO/VAX I, and the MICRO/PDP-11. The DR-216 may be operated with or in place of DEC Model MSV11-L, MMV11-D, MSV11-E, and MSV11-P series memories.

The DR-216 is completely compatible with all Q-BUS computers and all standard DEC Q-BUS peripheral devices. The DR-216 operates in computers with 16, 18, or 22 address lines.

The DR-216 is a standard-height, dual-width board, which contains the following: a Q-BUS interface, timing and control logic, refresh circuitry, a MOS storage array, parity generation and checking logic, and a control and status register (CSR).

The DR-216 supports block mode for multiple DMA transfers.

SECTION 2 - ELECTRICAL SPECIFICATIONS

2.1 CAPACITY

128K X 18 (256 KB) 256K X 18 (512 KB) 512K X 18 (1 MB) 1024K X 18 (2 MB)

Two parity storage bits for parity generation and checking are included.

2.2 CYCLE TIME

Cycle time is the interval from SYNCH being received on-board (output of bus receivers) to the end of memory busy. During this interval no other cycles may start. The maximum cycle times for the DR-216 are 316 ns for a Read cycle and 391 ns for a Write cycle. Figures 2-1 through 2-8 define the bus timing when the DR-216 is operated in a Q-BUS computer.

2.3 ACCESS AND DATA VALID TIMES

Access time for a memory cycle is defined as the interval from SYNCH being received on-board (output of bus receivers) to REPLYH being generated on-board (input of bus drivers). Data valid time is the interval from the assertion of SYNC to the moment when data from memory is present on BDALOO-BDAL15. This interval is measured at the connectors of the board. The following table summarizes both access and data valid times for various memory cycles:

	ACCESS TYPICAL	TIMES MAXIMUM	DATA VALI Typical	D TIMES MAXIMUM
DATI DATO(B)	80 85	90 121	160	210
CSR DATI CSR DATO	100 70	145 105	100	145

NOTE

Cycle, access, and data valid times assume the minimum time between SYNCH and DINH/DOUTH which is 25/50~ns.

Figure 2-1. DATI (Read)

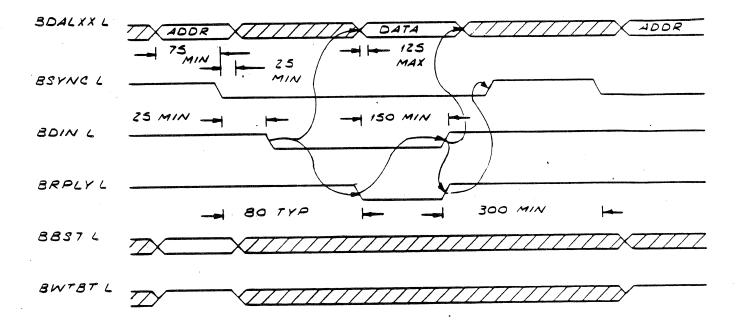


Figure 2-2. DATO (Write Word) or DATOB (Write Byte)

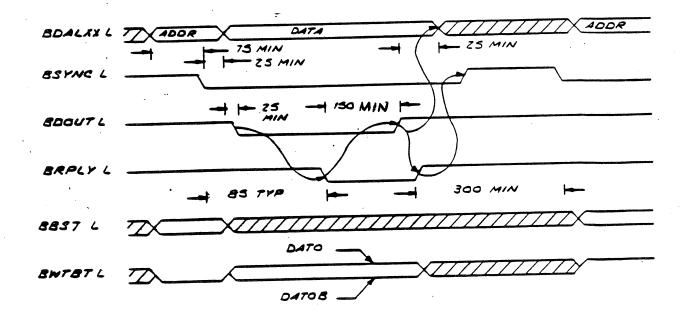


Figure 2-3. DATIO / DATIOB

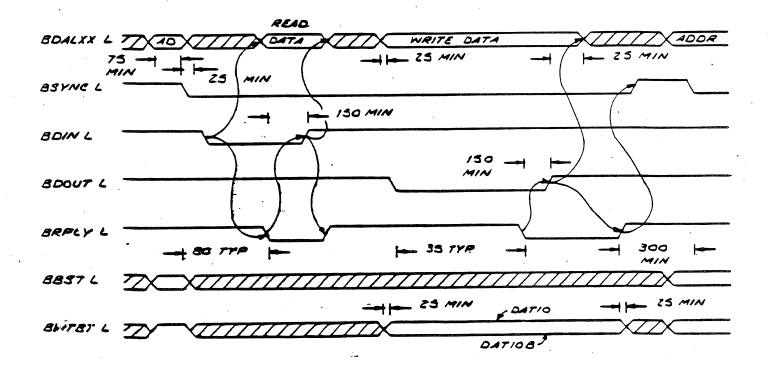
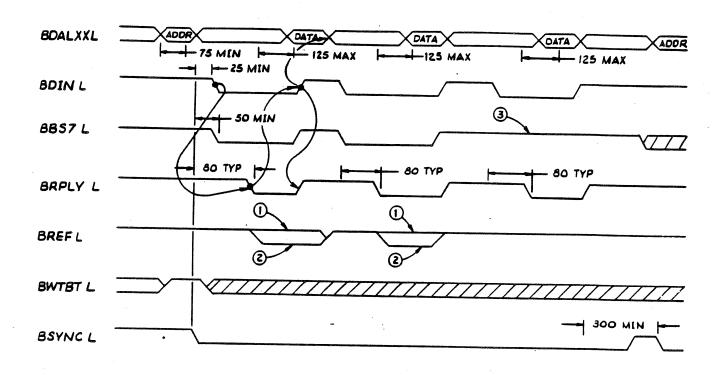
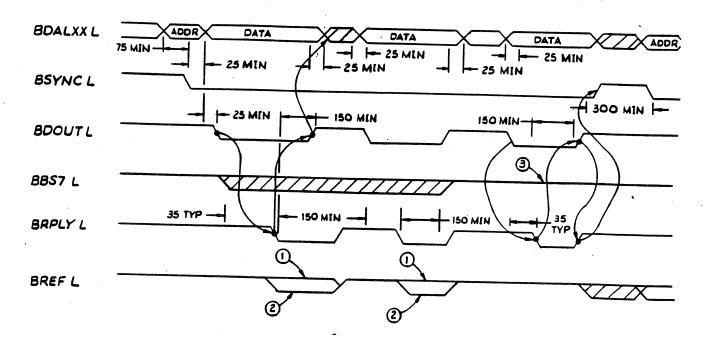


Figure 2-4. DATBI (Block Mode Read)



- 1 UNABLE TO PERFORM DATBI
- 2 ABLE TO PERFORM DATBI
- 3 LAST WORD TRANSFER

Figure 2-5. DATBO (Block Mode Write)



- 1 UNABLE TO PERFORM DATBO
- 2 ABLE TO PERFORM DATEO
- 3 LAST WORD OF TRANSFER

Figure 2-6. CSR DATI (Read)

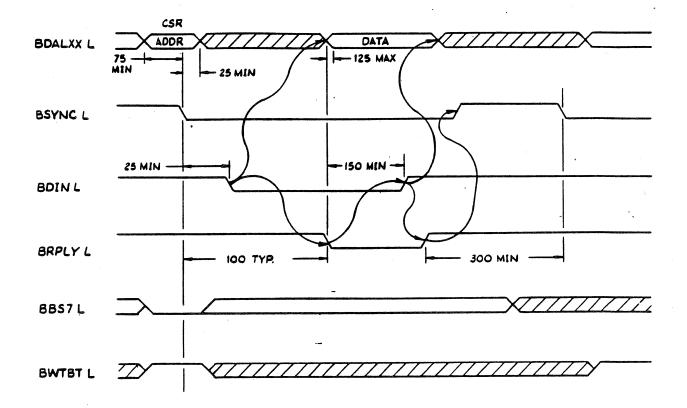


Figure 2-7. CSR DATO

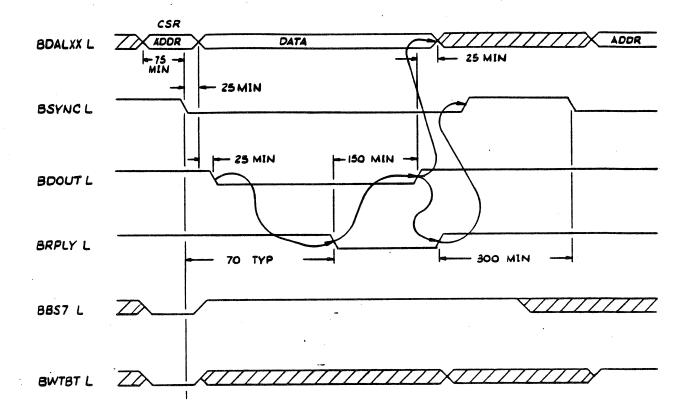
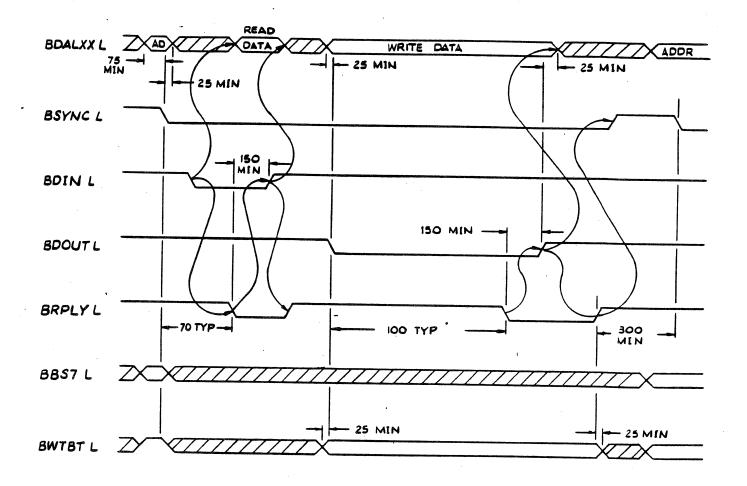


Figure 2-8. (Read-Modify-Write Word)



2.4 ADDRESSING

The DR-216 memory accepts 22 address lines. The first 16 address lines are time multiplexed with the data lines and are identified as BDALOL through BDAL15L. The extended address lines are identified as BDAL16-21L. BDALOL is used for upper or lower byte selection. BDAL1L through BDAL17L are decoded for 1 of 131,072 address locations within any memory module. BDAL13L through BDAL21 are used to set the initial address for a memory module. Addresses are offset in 8 KW increments using switches.

2.5 OPERATING MODES

The DR-216 performs the following operations:

Command	Operation
DATI DATO DATOB DATIO	Read Write Write Byte Read-Modify-Write
DATIOB DATBI DATBO	Read-Modify-Write Read-Modify-Write Byte Block Mode Read Block Mode Write

These operations are controlled by bus signals BSYNCL, BWTBT, BDALOL, BDINL, and BDOUTL. Figures 2-1 through 2-8 contain the timing diagrams for the above operations.

An additional mode, REFRESH, prevents loss of data stored in the NMOS storage chips. NMOS Random Access Memory (RAM) devices store data on the gate capacitance of a field-effect transistor (FET). A "1" is stored in the presence of charge and a "0" is stored in the absence of charge. The stored charge deteriorates over time and must be renewed on the DR-216 at least every two milliseconds. Therefore, one 1/128th of the memory (1/128th of each memory chip) is refreshed every 14 microseconds. This cycle is transparent to the CPU.

Refresh circuitry resides on the memory module. If a Read or Write cycle is requested during a refresh cycle, a maximum of $300\,$ nanoseconds is added to the total cycle time.

2.6 CONTROL AND STATUS REGISTER

The control and status register (CSR) enables program control of parity functions and contains diagnostic information if a parity error occurs. The CSR is read or written to via the Q-BUS. CSR addresses are jumper-selectable within the range 172100-172136 for a 16 bit address, 772100-772136 for an 18 bit address, and 17772100-17772136 for a 22 bit address configuration. Jumper E12 determines the CSR address.

The CSR bit assignments are shown below:

13 12 11 10 8 2 A17 A16 A15 A14 A13 A12 A11 PAR ERR NOT NOT WRT NOT ERR RTVL USED OR OR OR OR OR OR USED WRG USED ENA 0 0 A21 A20 A19 A18 PAR

NOTE:

The CSR can be disabled using a strappable jumper.

Parity Enable - Bit O

Enables parity error detection when set. The DR-216 asserts BDAL17L during data time of a DATI or DATIO cycle and allows the CPU to trap to 114g. This bit may be read or written via the Q-BUS and is cleared by BINIT.

Write-Wrong Parity - Bit 2

When set, bit 2 forces incorrect parity to be generated by the memory. Bit 2 is read or written to via the Q-BUS and is cleared by BINIT.

Error Address - Bits 5-11

These bits contain the most significant address bits within the memory location where a parity error has occurred. CSR bit 14 determines which addresses are read. Bits 5-11 may be read or written via the Q-BUS but are not cleared by BINIT.

Error Retrieval - Bit 14

Bit 14 determines which error addresses are read onto the Q-BUS. When bit 14 is reset, address lines All-Al7 are read. When bit 14 is set, Al8-A21 are read. Bit 14 should be locked in a reset position for systems with only 16 or 18 address lines. Bit 14 is read or written to from the Q-BUS and is cleared by BINIT.

Parity Error - Bit 15

Bit 15 is set when a parity error occurs. It does not cause a parity trap in the processor. Bit 15 may be read or written via the Q-BUS and is cleared by BINIT.

Unused Bits - Bits 1,3,4,12 and 13

These bits are not used and are always read as a logical zero.

2.7 POWER REQUIREMENTS

The DR-216 Memory System requires the same DC voltages as the MSV11-L DEC memory. The necessary logic to operate with battery backup is provided on the memory module (+5B-AV1). The voltage-current requirements for each $1024K \times 18$ memory assembly are as follows:

	Operating Amps	Standby Amps	Voltage Margin
+5 V	1.3	1.3	+5%
+5V Battery	1.0	.7	+5.%.
+5V Total	2.3	2.0	+5%

2.8 BUS SIGNALS

BDALOL through BDAL21L

Data/Address Lines

These 22 lines communicate address and data information. The device requesting the memory first places an address on these lines. Then the device either receives input data from the memory or outputs data to the memory over the same bus lines. Extended addresses BDAL16-21L enable addressing of up to 4MB of memory. BDAL16L is also used for parity error signal propagation.

BSYNCL

Synchronize

Asserted by the bus master to instruct the memory to accept address information on the BDAL bus.

BWTBT

Write/Byte

When asserted by the bus master prior to BSYNCL, it instructs memory to prepare for a DATO (Write) operation. If BWTBTL is asserted during BDOUTL in a DATO operation, then the operation becomes a DATOB (Write Byte) cycle.

BDCOKH

DC Power OK

BDCOKH is asserted by the power supply. BDCOKH inhibits all memory operation except Refresh cycles.

BDINL

Data Input

Asserted by the bus master when it is ready to accept data from memory. Memory must then respond with BRPLYL to complete the handshake.

BDOUTL

Data Out

Asserted by the bus master to indicate that the data headed for memory is valid on the BDAL bus lines. The memory must respond with BRPLYL to complete the handshake.

BRPLYL

Reply

Asserted by the memory to indicate to the bus master that data is available on the BDAL bus or that the memory has accepted data from the bus.

BBS7L

Bank 7 Select

Asserted by the bus master when the selected address is on the I/O page. BBS7L is also used by memory to select the CSR and disable normal memory operation.

BREFL

Refresh

Asserted during BDIN or BDOUT cycles to instruct the on-board address counter to increment, thus enabling a block mode transfer.

2.9 INDICATOR LAMPS

The DR-216 contains three LED indicator lamps, shown in Figure 3-1, which define the following conditions:

LED2 (RED) - When LED2 is lit, a parity error has occurred on the memory board. LED2 is reset (extinguished) by initializing the system with BINITL, or by writing a zero into bit 15 of the status register.

LED1 (RED) - When LED1 is lit, a memory cycle, is in progress.

LED3 (GREEN) - When LED3 is on, correct power is being supplied to memory. LED3 is powered by the +5 VB line. Thus, if the +5 VL supply fails, the LED remains lit if proper backup power exists.

2.10 OPTIONS

2.10.1 I/O Space

I/O space size is strappable for 4K, 2K, 1K and .5K words.

2.10.2 Battery Backup

The DR-216 provides the necessary jumper-selectable logic to operate with battery backup. Battery backup provides a +5 VB power line to maintain the RAM array.

2.10.3 External Parity Control

Strapping options enable the DR-216 to operate in systems where an external parity controller controls parity functions on all memories within the system.

SECTION 3 - MECHANICAL SPECIFICATIONS

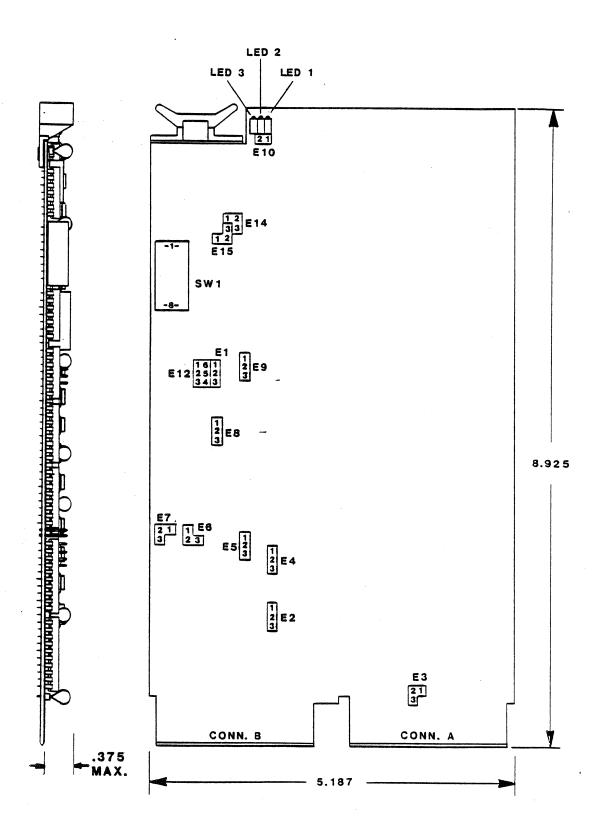
3.1 DIMENSIONS

The DR-216 fits into the Q-BUS chassis or equivalent, occupying a standard dual printed circuit board slot. The memory board dimensions are .466 in (11.84mm) x 8.92 in (226.57mm) x 5.186 in (131.72mm). See Figure 3-1.

3.2 WEIGHT

.72 pounds (.33 kg)

Figure 3-1. DR-216



SECTION 4 - ENVIRONMENTAL SPECIFICATIONS

4.1 TEMPERATURE

Operating: 0°C to $+55^{\circ}\text{C}$ Storage: -40°C to $+80^{\circ}\text{C}$

4.2 HUMIDITY

Operating: 0 to 90% (without condensation) Non-Operating: 0 to 95% (without condensation)

4.3 ALTITUDE

Operating: 1000 ft (300 m) below to 10,000 ft (3000 m) above

mean sea level

Non-Operating: 1000 ft (300 m) below to 20,000 ft (6000 m) above

mean sea level

4.4 VIBRATION

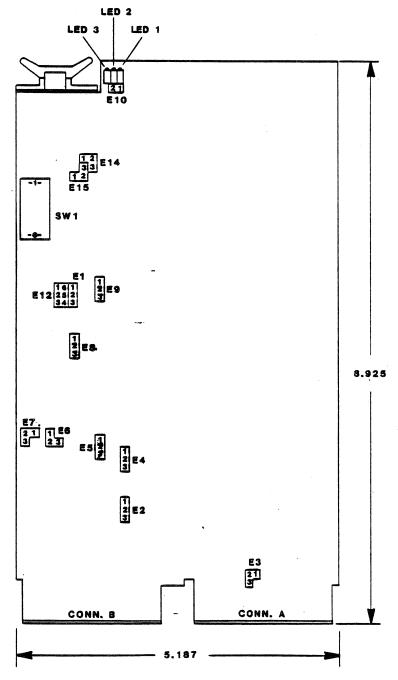
Withstands normal stresses encountered in transportation.

SECTION 5 - INSTALLATION

5.1 SWITCH SETTINGS/JUMPER OPTIONS

When installing the DR-216, set the starting address according to Table 5-1. Set the CSR address according to Table 5-2.

Figure 5-1. DR-216 Jumper Locations (Boards at REV E and later)



Jumper Options

Table 5-3 summarizes all jumper functions. Figures 5-1 and 5-2 detail the jumper locations for the different revision levels of artwork.

To determine which drawing to use, inspect switch 1. If switch 1 is an 8 position DIP, use Figure 5-1. If switch 1 is a 10 position DIP, use Figure 5-2. For boards with a 10 position switch, positions 9 and 10 are not used.

Figure 5-2. DR-216 Jumper Locations (Boards at REV D and earlier)

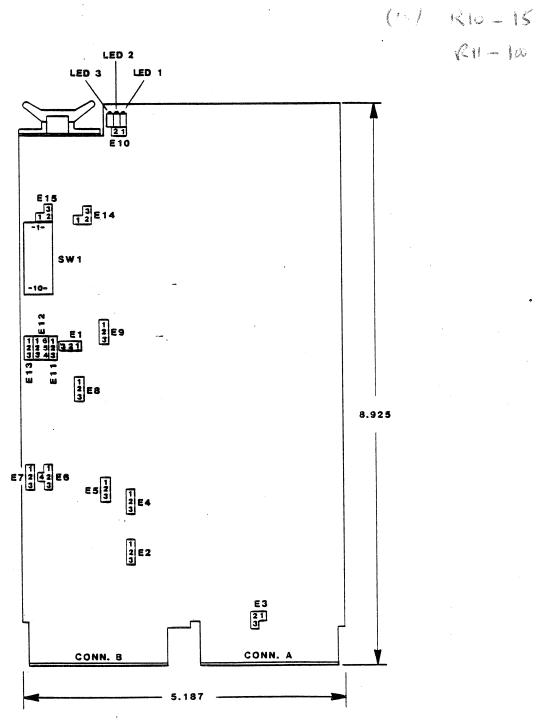


Table 5-1. Switch SW1

STARTING ADDRESS				
•	POS 8	POS 7	POS 6	POS 5
OKW	OFF	OFF	OFF	OFF
8 K W	0 N	OFF	OFF	OFF
16KW	0 F F	ON	OFF	OFF
24KW	0 N	ON	OFF	0 F F
32KW	0 F F	OFF	ON	0 F F
4 O K W	0 N	OFF	ON	0 F F
48KW	OFF	ON	ON	0 F F
56KW	ON	ON	ON	0 F F
64KW	0 F F	OFF	0 F F	0 N
72KW	ON	OFF	OFF	ON
80KW	OFF	ON	OFF	0 N
88KW	0 N	ON	OFF	ON
96KW	0 F F	OFF	ON	ON
104KW	0 N	OFF	ON	ON
112KW	OFF	ON	O N	O N
120KW	ON	ON	ON	ON

For all other settings use equal increments of 128KW plus the appropriate 8KW increment from the above table.

			POS 4	POS 3	POS 2	POS 1
0	-	128KW	0 F F	OFF	0 F F	OFF
128	-	256KW	ON	0 F F	OFF	OFF
256	-	384KW	0 F F	ON	OFF	OFF
384	•	512KW	0 N	ON	OFF	OFF
512	-	640KW	0 F F	OFF	0 N	OFF
640	-	768KW	0 N	OFF	ON	OFF
768	-	896KW	OFF	ON	ON	OFF
896	-	1024KW	. ON	0 N	ON	OFF
1024	-	1152KW	0 F F	OFF	OFF	ON
1152	-	1280KW	ON	0 F F	OFF	ON
1280	-	1408KW	0 F F	ON	OFF	ON
1408	-	1536KW	ON	0 N	OFF	ON
1536	_	1664KW	0 F F	OFF	ON	ON
1664	-	1792KW	0 N	OFF	ON	ON
1792	-	1920KW	0 F F	0 N	ON	ON
1920	-	2048KW	0 N	0 N	ON	ON

ON = Closed OFF = Open

Table 5-2. CSR Address Select

Jumper E12

16 Bit Address	18 Bit Address	22 Bit Address	Pin 1 to 2	Pin 2 to 3	Pin 4 to 5	Pin 5 to6
172100 172102 172104 172106 172110 172112 172114 172116 172120 172122 172124 172126 172130 172132	772100 772102 772104 772106 772110 772112 772114 772116 772120 772122 772124 772126 772130 772132	17772100 17772102 17772104 17772106 17772110 17772112 17772114 17772116 17772120 17772122 17772124 17772126 17772130 17772132 17772132	OUT IN OUT IN OUT IN OUT IN OUT IN OUT IN	OUT OUT IN IN OUT IN OUT IN IN OUT IN	OUT OUT OUT IN IN IN IN OUT OUT OUT OUT IN	OUT OUT OUT OUT OUT OUT OUT IN IN IN IN IN IN
172136	772136	17772136	IN	IN	IN	I N I N

NOTE:

E5 Pin 2 to 3 disables CSR selection. E7 Pin 2 to 3 must be installed for 16 or 18 bit address operation.

Table 5-3. Jumper Function Summary

FUNCTION	IN	OUT
CSR Selection Disable CSR Enable CSR	E5-2 to E5-3 E5-1 to E5-2	E5-1 to E5-2 E5-2 to E5-3
Parity Error Report Non-CSR With CSR		E1-1 to E1-2 E1-2 to E1-3
Write Wrong Parity Enable Disable	Enable E6-1 to E6-2 E6-2 to E6-3	E6-2 to E6-3 E6-1 to E6-2
Parity Disable Enable	E4-2 to E4-3 E4-1 to E4-2	E4-1 to E4-2 E4-2 to E4-3
Memory Size Fully Populated Half Populated		E14-2 to E14-3 E14-1 to E14-2
Addressing 16/18 Bit Address 22 Bit Address	E7-2 to E7-3 E7-1 to E7-2	E7-1 to E7-2 E7-2 to E7-3
Battery Backup Battery Backup No Battery Backup	E3-2 to E3-3 E3-1 to E3-2	E3-1 to E3-2 E3-2 to E3-3
Block Mode Enable Disable	E2-1 to E2-2 E2-2 to E2-3	E2-2 to E2-3 E2-1 to E2-2
I/O Space Size 4KW	E8-1 to E8-2 E8-2 to E8-3 E9-1 to E9-2	 E9-2 to E9-3
2 K W	E8-2 to E8-3 E9-1 to E9-2	E8-1 to E8-2 E9-2 to E9-3
1 K W	E8-1 to E8-2 E9-1 to E9-2	E8-2 to E8-3 E9-2 to E9-3
.5 KW	 E9-1 to E9-2	E8-1 to E8-2, E8-2 to E8-3 F9-2 to E9-3

Table 5-3. (Cont'd)

FUNCTION	IN	OUT
64K/256K DRAMS 64K	E15-1 to E15-2 E10-1 to E10-2	E15-2 to E15-3
256K	E15-2 to E15-3	E15-1 to E15-2 E10-1 to E10-2

5.2 COMPUTER INSTALLATION

The DR-216 plugs into a dual-width Q-Bus (LSI-11) slot. Install the DR-216 into a LSI-11 computer as follows:

- 1. Set starting address. Take care not to overlap memory module addresses. If they do, the computer will not boot.
- 2. Set the CSR address if CSR is enabled. Each CSR must have a unique address. If more than one CSR is used, the CSR addresses must be in increasing order relative to the memory which it is monitoring. For example, if memory locations 0000 to 512K words have a CSR located at address 17772104, the next CSR must be at an address above 17772104 (i.e., 17772106, 17772110). In this configuration, CSR addresses 17772100 and 17772102 cannot be used.
- 3. Plug the DR-216 into the computer.

NOTE:

Due to a design change, jumper point E4 has been eliminated and should no longer be inserted on assembly numbers 61545, 61546, 61548 and 61549 revision levels C7 or D4. The assembly number and revision level are stamped on the solder side of the board along one edge.

All other revision levels still require jumper E4-1 to E4-2 to be inserted for parity to be enabled.

5.3 DIAGNOSTICS

The DR-216 is compatible with all DEC memory diagnostics. However some diagnostics will not exercise the entire memory board. The following is a list of recommended diagnostics for the DR-216:

11/23, 11,23+, 11/73 Processors and the MicroPDP.

Use either diagnostic ZMSD?? or VMSA??.

NOTE

The 11/73 processor has an on-board cache that must be disabled prior to running any diagnostics. The steps are as follows:

- 1. Boot the operating system, XXDP or XXDP+.
- 2. After the prompt, a period (.), press the break key if enabled or the halt switch on the front panel.
- 3. Deposit 14 in location 17777746, the cache control register. This will disable the cache on the 11/73.
- 4. Type P to return to XXDP or XXDP+. Do not use the GO command because a bus INIT will be issued which will clear the cache control register.

MICROVAX I

Use diagnostic EHXMS.

NOTE

The 2 megabyte DR-216 will fail with this diagnostic. The error message will be:

Error during test 2, subtest 5
Memory Configuration Test, Memory/CSR Correlation Test
Part 1
Too few memory CSRs present; expected at least 2, found 1

This error will occur on all boards larger than 1 megabyte, including DEC's. Later versions of the diagnostic should have this problem corrected. Presently, the only way around this problem is to disable the halt feature of the diagnostic.

5.3.1 Determining Bad Ram Locations

If a diagnostic uncovers a bad ram location it should be replaced to insure data integrity.

All DRAMs are socketed so replacement can be done with little trouble. To find the location of a defeative DRAM as the process.

trouble. To find the location of a defective DRAM on the DR-216 follow the procedure outlined below. All addresses are given in both octal and decimal to facilitate replacement.

All addresses are given in both octal and decimal to facilitate replacement.

- 1. Subtract the starting address of the DR-216 memory board from the address of the bad DRAM.
- 2. Determine which row the bad DRAM is in by using the appropriate table below. Table 5-4 is for DR-216 memory boards populated with 64k DRAMs and Table 5-5 is for boards with 256k DRAMs. Use only the first two entries in a table for half populated boards.

Table 5-4. 64K DRAMs

Address				
Octal	Decimal	Row		
0-377777	0-128KB	А		
400000-777777	128KB-256KB	С		
1000000-1377777	256KB-384KB	В		
1400000-1777777	384KB-512KB	D		

Table 5-5. 256K DRAMs

Address		
Octal	Decimal	Row
0-177777	0-512KB	А
2000000-3777777	512KB-1024KB	C
4000000-5777777	1024KB-1536KB	В
6000000-7777777	1536KB-2048KB	D

3. The row letter is silkscreened on the edge of the board opposite from the connector fingers. The bit numbers are silkscreened down the side of the DRAM array near the long edge of the board. The parity bits are designated by PO and P1.

5.4 TROUBLESHOOTING GUIDE

The DR-216 is completely tested prior to shipping. However, sometimes problems do occur and the board fails to function correctly. If a problem does arise, the following sequence of steps should be followed to isolate the fault.

- 1. With power off, remove the DR-216 from the backplane and visually inspect it for damaged components and other obvious problems.
- 2. Check the strapping of the board against Table 5-3, and use Table 5-1 to insure that switch 1 (SW1) is set to the proper starting address.

3. Turn power on and check the backplane for proper voltages at the following pins:

- 4. Remove power from the backplane and replace the DR-216 in the computer. Turn the computer back on and verify that the DR-216 can be read from and written to under ODT.
- 5. If the fault has been isolated to the DR-216, run one of the diagnostics recommended in section 5.3. If the system will not boot with the DR-216, put a working memory board at location 000000 and set the address of the DR-216 in question to start above that of the lower board. Now boot and run the diagnostic.
- 6. If the problem persists, call the Dataram sales representative for help.

SECTION 6 - PROGRAMMING

A programmable control register, the control-and-status register (CSR) resides on the DR-216. The CSR monitors parity, and contains the diagnostic information if a parity error occurs. Programming involves addressing the CSR during a DATI, DATO, and DATIO bus cycle (see table 5-2). CSR bit assignments are described in Section 2.6.

SECTION 7 - THEORY OF OPERATION

The DR-216 operates in any of DEC's LSI-11 bus (Q-BUS) compatible computers. It performs DATI, DATO(B), DATIO(B), DATBO, and DATBI bus cycles as a slave device for any Q-BUS master. The following description details the operation of the DR-216 in a Q-BUS compatible computer.

7.1 HARDWARE

7.1.1 Bus Signals

BDALOO....used to select a single byte in a word when BWTBTL is asserted during a write operation. Data bit 00 is multiplexed on this line during the data portion of a memory cycle.

BDAL01-BDAL15L....multiplexed data and address lines.

BDAL16-BDAL21L....upper address lines used to extend addressing capability to 4 megabytes. BDAL16 is also used as a parity error signal during the data portion of a read cycle.

BSYNCL....a synchronizing control signal from the bus master to memory. BSYNCL indicates address information is stable on the bus and initiates a memory cycle.

BWTBTL....this signal is asserted during the addressing portion of a memory access cycle to signal a DATI or DATIO cycle is going to take place. It is asserted during the data portion of a memory cycle for a byte write operation.

BBS7-L...a signal from the bus master that it is accessing data in the I/O page, 28K-32KW. It is also used to signify a DATBI cycle.

BDCOKH....a high asserted signal signifying that DC power is stable.

BDINL...a request from the bus master for memory read data to be placed on the BDAL bus lines. The memory must answer with BRPLYL for completion of the memory cycle.

BDOUTL....a request from the bus master for the memory to accept write data from the bus and store the data in memory. The memory must answer with BRPLYL to complete the memory cycle.

BRPLYL...a required response from the memory indicating read data is valid or write data has been accepted from the bus.

BREFL....a response from the memory indicating that it is able to continue a block mode transfer, either a DATBI or DATBO cycle.

7.1.2 Internal Signals

RDYN....asserted by the refresh controller when it is ready to do a refresh.

RDYD....RDYN delayed 100 ns and inverted, used for refresh arbitration.

REFREQ....signals refresh controller to start a refresh cycle.

VALADD....asserted if the bus master is addressing the memory board.

START....assertion of START initiates the DRAM timing chain.

A0-A8....address lines of DRAM array.

D2....timing pulse used to multiplex the row and column addresses onto A0-A8.

RASAN, RASBN, RASCN, RASDN....row address strobe, low asserted signal that determines which row is being accessed. Used to strobe row addresses into the DRAM array.

CASON, CASIN....column address strobe, asserted low when column addresses are valid on AO-A8.

WRAN, WRBN....write enable lines to the RAM array. For word writes, both WRAN and WRBN are asserted and for byte writes only one line is asserted.

RDCSRDN....a low asserted signal which gates the CSR data onto the internal data bus.

WRCSR....asserted to during a CSR write cycle to clock data into the CSR.

INCOUNT....leading edge increments the counter during a block mode operation.

MAXN....asserted low if the memory board cannot do another block mode transfer.

LATWTBT....WTBT latched on the leading edge of SYNCH, used to determine if the cycle is a memory read or memory write.

DIOLAT....used to determine which byte is being accessed during a byte write cycle.

LADOO-LAD21....addresses from the bus.

DIOOO-DIO15....internal data bus.

CSRH....asserted when the CSR address is placed on the bus during the addressing portion of a memory access cycle.

IOSPCH....asserted when the address on the bus is in the I/O page (BBS7 asserted).

7.2 BLOCK DIAGRAM

The circuitry on the DR-216 can be broken up into five functional groups: the Q-BUS transceivers, the DRAM array, the CSR and associated control, control logic and refresh control. A functional block diagram of the DR-216 illustrating the five groups is on page one of the schematic.

7.2.1 Q-BUS Transceivers

The Q-BUS transceivers buffer all signal lines between the Q-BUS and the DR-216 memory board. This includes all data, address and control signals. The types of transceivers used include AM2908, DM8641 and 74LS340.

7.2.2 DRAM Array

The DRAM array occupies most of the board area and is laid out as four rows of eighteen chips. Each row accommodates sixteen data bits and two parity bits. In a half populated board only two of the four rows are occupied by DRAMs. The DR-216 is populated with either $64k \times 1$ or $256k \times 1$ DRAMs depending on the size ordered.

7.2.3 CSR And Associated Control

The CSR control logic monitors the DRAM array for possible parity errors. If an error does occur, the address of the location where the error occurred is loaded into the CSR and the processor is notified using BDAL16L. The CSR is also used in a diagnostic capability by many diagnostics and operating systems to size the board and determine if any DRAM locations are bad.

7.2.4 Control Logic

The control logic is shown on the block diagram as five separate blocks. These blocks are labeled Timing & Control, Memory Select & RAS Decode, CAS & WR Drivers, Address MUX & RAM Drive and Block Counter & Address Latch. This logic ties together the rest of the circuitry on the board so that the DR-216 will function properly. The control logic's main function is to arbitrate between a refresh cycle and a memory access cycle. Other functions include determining if the board is being accessed, determining which row the data is in, and generating parity to be written during a write cycle. The control logic is implemented in two high-speed PALs and two FPLAs.

7.2.5 Refresh Control

The refresh control signals the control logic when it is time to do a refresh operation. It also generates the control signals needed to do the refresh operation including RAS and the address. The refresh control is composed of one chip, a 74LS603 and a few descrete components.

7.3 MODES OF OPERATION

7.3.1 DATI (Read)

During a DATI cycle, the memory reads a full word of data at a location determined by the bus master and transfers this data onto the bus.

To initiate a read cycle, the bus master places the address (BDAL00-BDAL21) of the memory location to be accessed on the bus. At the same time, it asserts BWTBTL to signal a read operation and also BBS7L if the memory location resides in the I/O page. A minimum of 75 ns later the bus master asserts BSYNCL to start the memory access cycle. It then asserts BDINL a minimum of 25 ns after the assertion of BSYNCL and waits for the memory to assert BRPLYL to signify valid data on BDAL00-BDAL15.

The address, BWTBTL, and BBS7L is received by the memory Q-BUS transceivers and is latched by the address latches on the leading edge of SYNCH. If the address is within the memory space of the board, the address selection logic asserts VALADD. The control logic starts the DRAM timing chain if the latched WTBT (LATWTBT) and VALADD signals are asserted. The timing chain generates the control signals; RASXN, CASON, and CASIN which are routed to the ram array to access one word of data. The selected word is clocked into the Q-BUS transceivers and gated onto the bus. The memory board answers BDINL with BRPLYL a maximum of 125 ns before the data is available on the bus. After the master has received the data, it removes BDINL from the bus and the memory board negates BRPLYL. The bus master is now free to start another memory cycle a minimum of 300 ns after the negation of BRPLYL.

7.3.2 DATO (Write)

In a DATO cycle, the memory accepts a full word of data and stores it at the location specified by the bus master. Valid address information is placed on the bus by the bus master at least 75 ns before it asserts BSYNCL.

The address, BWTBTL, and BBS7L is received by the memory Q-BUS transceivers and is latched by the address latches on the leading edge of SYNCH. If the address is within the memory space of the board, the address selection logic asserts VALADD. Since LATWTBT is not asserted, the control logic waits for DOUTH to be asserted

before initiating the DRAM memory timing chain. The memory

boards answers BDOUTL with BRPLYL to indicate that it has accepted the data. The master then removes BDOUTL from the bus and the memory board negates BRPLYL allowing the master to initiate another memory cycle after a 300 ns delay.

7.3.3 DATOB (Write Byte)

The DATOB cycle is the same as the DATO cycle except that the master asserts BWTBTL at the same time as BDOUTL to indicate that only a byte (8 bits) of data is to be written to memory. The memory board uses BDALOO to determine which byte the master wants to write data to. Data in the other byte of the word is not affected.

7.3.4 DATIO (Read-Modify-Write)

During a DATIO cycle, data is read from memory, modified by the bus master and then written back to the same location.

The first half of a DATIO cycle is the same as a DATI cycle, however a minimum of 300 ns after BRPLYL is negated by the memory board the bus master starts the write portion of the cycle by asserting BDOUTL. The memory control logic treats the write portion as if it were a separate DATO cycle. The assertion of DOUTH starts the DRAM timing chain and BRPLYL is asserted by the memory board to signify that the data has been accepted. The removal of BDOUTL from the bus by the bus master causes the memory board to remove BRPLYL from the bus and the master is now free to start another memory cycle after a minimum delay of 300ns.

7.3.5 DATIOB (Read-Modify-Write Byte)

This cycle is identical to the DATIO cycle outlined above except that a byte of data is written during the write portion of the cycle. BWTBTL is asserted during the time that BDOUTL is asserted to signify a DATIOB cycle. If BDALOO is asserted, byte 1 (bits 8-15) will be written, otherwise byte 0 (bits 0-7) is written.

7.3.6 Block Mode

Throughput of a Q-BUS based computer can be significantly increased by taking advantage of the DR-216's block-mode capabilities. Presently, there are many DMA devices that use block-mode to transfer data to and from memory. The MICROVAX I also uses block-mode in most of its CPU memory accesses. In a block-mode transfer, the address is placed on the bus and then up to sixteen sequential data transfers are executed before another address must be placed on the bus. A counter on the DR-216 is incremented automatically after every transfer, insuring that the accesses are to the correct location.

7.3.6.1 DATBI (Block Mode Read)

To initiate a DATBI cycle, the bus master first places the addresses on the bus and asserts BWTBTL. A minimum of 75 ns later BSYNCL can be asserted by the bus master to start the cycle. For each transfer desired, the bus master asserts BDINL and waits for the memory to answer with BRPLYL. If another transfer is desired after the present one, the bus master also asserts BBS7L along with BDINL. The bus master waits 300ns after the trailing edge of the last BRPLYL before starting another cycle.

The memory board receives the address from the bus and decodes it to determine if it is being addressed. If the memory location being accessed resides on the board the DRAM timing chain is started because BWTBTL was asserted along with the addresses. In response to BDINL being asserted by the bus master, the board asserts BRPLYL signifying that the data is valid on the bus. Along with BRPLYL, the memory board asserts BREFL if it can continue with the block-mode transfer. If BBS7L is asserted along with BDINL, the board prepares to do another read cycle at the next word address. When the board can no longer continue with the block-mode transfer, it does not assert BREFL with reply and the bus master halts the DATBI cycle after the transfer in progress.

7.3.6.2 DATBO (Block Mode Write)

In a DATBO cycle, the bus master places the addresses on the bus at least 75 ns before the start of the cycle. The master then places the data on the bus (BDALOO-BDAL15) a minimum of 25 ns before asserting BDOUTL to signal the transfer. After asserting BDOUTL, it then waits for the assertion of BRPLYL from the memory before removing BDOUTL and then the data from the bus. If the bus master has more data to transfer, and BREFL was asserted by the memory along with BRPLYL, it will again place the data on the bus and assert BDOUTL. This process continues until the memory does not assert BREFL with BRPLYL, the bus master is finished writing data to memory, or the maximum number of transfers (16) has occurred.

7.3.7 Refresh

Refresh is necessary to prevent loss of data stored in the NMOS memory chips. NMOS DRAM devices store data on the parasitic gate capacitance of a field-effect-transistor. A "1" (high) is stored as the absence of charge and a "0" (low) is stored by charging the parasitic capacitor. The stored charge deteriorates due to leakage and must be renewed at least once every 4 ms. The memory chip is divided into 128 rows and each row is refreshed every 14.5 microseconds. This refresh operation is transparent to the bus master. If the bus and the refresh operation both try to

access the DRAMS, the bus will win and the refresh operation is delayed until the memory access is finished. If a refresh

operation is in progress and the bus master tries to access the memory, the cycle will be delayed until the refresh operation is completed. In this case the memory access cycle will be delayed a maximum of $400~\rm ns$.

All refresh operations are controlled by a single chip. This refresh controller signals when a refresh operation is needed. If the memory is not being accessed, the control logic asserts REFREQ, signaling the refresh controller to proceed with the refresh operation.

SECTION 8 - PART NUMBERS/DOCUMENTATION

8.1 PART NUMBERS

The following Dataram part numbers have been assigned to the DR-216 Memory System:

Part Number	Description					
61548	DR-216,	128K >	< 18	(256KB)		
61545	DR-216,	256K >	(18	(512KB)		
61549 •	DR-216,	512K >	(18	(1 MB)		
61546	DR-216.	1024K V	1.8	(2 MR)		

8.2 DOCUMENTATION

The following documentation numbers have been assigned to the DR-216 Memory System:

Part Number	Description
03445	Schematic Drawings
61545	Assembly Drawing, DR-216
61545	Bill of Materials, DR-216

REV.	2				RE'	VISIONS			
#	0	SYM.	SHEET		DES	CRIPTION		APPROV.	DATE
ŀ	-	×ø		PRELIMINARY	RELEASE			PTD	8/2/84
	4	ΑØ		RELEASED TO	O PRODUCTIO	N		#BC	1-4-84
5	9	Α1		ECN 3872					
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		В1		ECN 3896					
DWG. NO.	SHEET	В2		ECN 3897		•			
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		В4		ECN 3900					
•		B 5		ECN 3902					
		В6		ECN 3919					
		В7		ECN 3920					
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		FØ		ECN4029				 	8/30/85
		F1 F2 G0 G1		ECN 4063 ECN 4064 ECN 4068 ECN 4084					1/29/86
1	Ĺ	G2		ECN 4136				JLW	1/27/86

8.2.84

JEJ	7.11.84	BILL OF MATERIALS		
CHECKED	DATE \$ 2.84	DR-216 256K X 18		
APPROVED	8.2.84 4.30.25 DATE 2JAN85	DATARAM	DWG. NO. 61545 SHEET 1 OF 4	GZ

TITLE: B/M DR-216 256K X 18

ITEM NO	QTY	PART NUMBER	DESCRIPTION	REFERENCE NOTES
1	2	18401	LED RED PC MT W/INTL RES	LED 1,2
2	1	18408	LED GREEN PC MT W/INTL RES	LED 3
3	72	12331	CAP CER AXL .1UF -20/+80%	A0-A15,AP0,AP1,B0-B15,BP0,BP1,
4	1	12343	CAP CER .001UF <u>+</u> 10%	C3 C0-C15,CP0,CP1,D0-D15,DP0,
5	2	12602	CAP SIL MICA 330PF ±5%	C4,20
6	19	18113	DIODE SILICON SWITCHING	CR1,3-20
7	10	12128	CAP TANT 15UF 16V	C 6,7,8,10,12,14,15,17,21,23
8	6	12316	CAP CER 0.1UF <u>+</u> 20%	C9, 13, 16, 18, 19, 24
9	1	12609	CAP SIL MICA 240PF +5%	C 5
10	1	12611	CAP SIL MICA 270PF ±5%	C 2
11	1	10113	RES CC 1/4W 1K OHMS 5%	R 5
12	1	10602	RES CC 1/4W 120 OHMS 5%	R 9
13	1	12326	CAP CER 0.1UF +20%	C 2 2
14		•	NOT USED	R10
15	1		RES SAT	R1
16	1	10119	RES CC 1/4W 3.3K OHMS 5%	R 2
17	1	10118	RES CC 1/4W 2.2K OHMS 5%	R3
18	1	14511	INDUCTOR 22 UH (DD)	L1
19	1	16345	IC 8641 QUAD UNIBUS XCVR	Z1
20	5	16380	IC 2908 INTFC XCVR	Z8,9,10,11,13
21	72	16940	IC DYNAMIC RAM 64K X 1	· A0-15,AP0,AP1,B0-B15,BP0,BP1,
				CO-15,CP0,CP1,D0-D15,DP0,DP1
22	72	23084	SOCKET IC 16 PIN OPEN FRAME LOW PROFILE ST	A0-15,AP0,AP1,B0-B15,BP0,BP1,
				C0-15,CP0,CP1,D0-15,DP0,DP1
23	. 1	16291	IC 74LS603 64K RAM REFRESH CONTROLLER	Z 2
24	1	16271	IC 74LS340 OCT INV BFR 3 STAT ST	Z4

*INDICATES PART TO BE FROM SUGGESTED MANUFACTURER ONLY.



DWG. NO. 61545 B/M

G2

TITLE: B/M DR-216 256K X 18

NO	QTY	PART NUMBER	DESCRIPTION	REFERENCE NOTES
25	1	16558	IC 74S135 QUAD EXCL OR/NOR	Z24
26	1	16573	IC 74AS646 OCT XCVR/REG	Z18
27	2	16574	IC 74S730/2965 OCT 3 STAT RAM DRVR	Z3,31
28	1	16511	IC 74S260 DUAL 5I/P NOR	Z 2 0
29	1	16514	IC 74S38 QUAD 2I/P NAND	Z32
30	2	16153	IC 74F373 OCTAL LATCH TS	Z7,14
31	1	16140	IC 74F191 U/D BIN CTR	Z12
32	1	16144	IC 74F244 OCTAL BUS/LINE DR	Z15
33	1	16154	IC 74F374 OCTAL D F/F TS	Z17
34	1	16134	IC 74F174 HEX D F/F W/COM RST	Z19
35	2	16160	IC 74F14 HEX ST INV	Z21,29
36	1	16119	IC 74F74 DUAL D TYPE F/F	Z34 ·
37	1	16117	IC 74F32 QUAD 2I/P OR GATE	Z27
38	2	16151	IC 74F283 4 BIT FULL ADDER	Z26,30
39	2	16150	IC 74F280 9 BIT PARITY GEN CHECK	Z23,28
40	2	16148	IC 74F257 QUAD 2I/P MUX TS	Z5,6
41	. 2	17702	IC 16H8A PAL UNPROG	FOR ITEMS 45,48
42	2	16957	IC 82S153 FPLA 3 STAT UNPROG	FOR ITEMS 44,47
43			NOT USED	
44	REF	08738 C	PROG CSR CONTROL	Z16
45	REF	08739 C	PROG CYCLE CONTROL	Z25
46	1	16116	IC 74F20 DUAL 4I/P NAND	Z27A
47	REF	08741 A	PROG CSR DECODING	Z22
48	REF	08742 B	PROG RAS/CYCLE DECODING	Z33
49	1	22917	SWITCH DIP 8 POS LOW PROF	SW1
50	33	22623	CONT MALE	E1-9,12

*INDICATES PART TO BE FROM SUGGESTED MANUFACTURER ONLY.

DATARAM CORPORATION
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NEW JERSEY

DWG. NO. 61545 B/M SHEET

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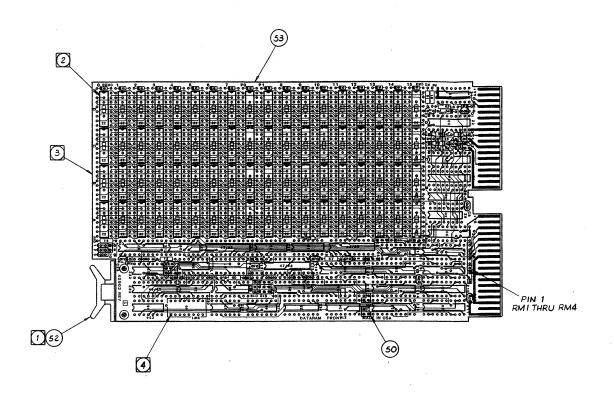
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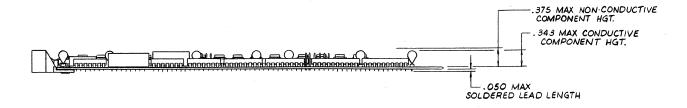
NO	QTY	PART NUMBER	DESCRIPTION	REFERENCE NOTES
51	1	14108	DELAY LINE DIGITAL 150NS	DL1
52	1	27434	CARD HANDLE LOW PROFILE	
53	1	40903	P.C.B. DR-216	
54	1	11105	RES MDL 10K OHMS 6 PIN	RM1
55	1	11993	RES MDL 10K OHMS 2%	RM2
56	1	11108	RES MDL 470 OHMS 6 PIN	RM4
57	1	10111	RES CC 1/4W 470 OHMS 5%	R8
58	1	10152	RES CC 1/4W 750 OHMS 5%	R6
59	A/R	24305	WIRE TINNED COPPER BUS 30 AWG	
60			NOT USED	R11
61	1	10105	RES CC 1/4W 100 OHMS 5%	R4
62	1	10111	RES CC 1/4W 470 OHMS 5%	R12
63	1	10121	RES CC 1/4W 4.7K OHMS 5%	R13
64	1	18214	DIODE ZENER 1N703A 3.3V	CR2
65	1	20103	XSTR PNP SWG 2N4403	Q1
66	A/R	24504	WIRE SOL GRN 30 AWG WW	
67	1	11956	RES MDL 10K OHMS	RM3
	·			
×	REF	06510	INSTALLATION GUIDE	
×	REF	02263	PRODUCT SPECIFICATION DR-216	
ж	REF	05187	TEST SPECIFICATION DR-216	
×	REF	03445	SCHEMATIC DR-216	

*INDICATES PART TO BE FROM SUGGESTED MANUFACTURER ONLY.



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NOTES:

- INSTALL AFTER FLOW SOLDER.
- [2] INSTALL ITEM 22 (SOCKETS) PRIOR TO INSTALLING ITEM 21 (INTEGRATED CIRCUIT).
- MARK THE DATARAM ASSY. NO., REV LEVEL, SERIAL NO., AND DATE CODE APPROX. WHERE SHOWN. CHARACTERS SHALL BE .10 MIN. HIGH AND LEGIBLE.
- SQUARE PAD DENOTES PIN 1 ON "E" POINTS, SWI AND DL1.
- 5. JUMPER THE FOLLOWING USING ITEM 59: E10-1 TO E10-2, E14-1 TO E14-2 AND E15-1 TO E15-2.
- 6. WIRE WRAP THE FOLLOWING USING ITEM 66: E1-1 TO E1-2, E2-1 TO E2-2, E3-1 TO E3-2, E4-1 TO E4-2, E5-1 TO E5-2, E6-1 TO E6-2, E7-1 TO E7-2, E9-1 TO E9-2, & AFTER TEST E8-1 TO E8-2, E8-2 TO E8-3.

	UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES TOLERANCES ARE: FRACTIONS DECIMALS ANGLE	CONTRACT NO.		(DATA CRANBL	RAM CORPO	PRATION NEW JERSEY
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	₿5	ECN 3902		
	86	ECN 3919	_	
	87	ECN 3920		
	Co	ECN 3931	1.,	DR
	CI	ECN 3946 JEJ	4/17/85	Ham
	Cz	ECN 3960		V .
	Сs	ECN 3961	_	
	Do	ECN 3963	_	
	Dı	ECN 3968		
	Dz	ECN 3976	_	
	Dз	ECN 3993	_	
	D4	ECN 3997	1.0/05	DSM
	Eo	ECN 3998 (REDRAWN) JEJ	4/25/85	7
	Eı	ECN 4006	7/15/85	4.84
	FO	ECN 4029 BL	8/30/85	JLW
	FI	ECN 4063		
	F2	ECN 4064		
	GΦ	ECN 4068		
	G1	ECN 4084		
	GZ	ECN 4136 .	1/29/86	JLW

